First indent layer is the name of the auton routine

Italics tell drive team how to set up

1. Nothingw
   1. *Doesn’t matter*
   2. Nothing moves
2. Drive
   1. *Approximately perpendicular to Initiation Line*
   2. Drive 30% throttle **forward** for 5 seconds
3. Shoot-Drive Backward
   1. *Point shooter at center of Power Port*
   2. Rev shooter to Initiation line speed
   3. Run shooter and Index for 5 seconds
   4. Drive 30% throttle **backwards** for 5 seconds
4. Shoot-Drive Forward
   1. *Point shooter at center of Power Port*
   2. Rev shooter to Initiation line speed
   3. Run Shooter and Index for 5 seconds
   4. Drive **forward** 4 feet
5. Shield Generator Balls
   1. *Place robot in front of ball closest to corner of Shield Generator square with initiation line*
   2. Auto-Align to Power Port and push out intake
   3. Rev shooter to Initiation line speed
   4. Run Shooter and Index
   5. Turn to -180 degrees
   6. Drive 7.22 ft. with Intake motors at 100%
   7. Turn to -240 degrees
   8. Drive 4.5 ft to collect all 3 balls
   9. Turn to -390 degrees
   10. Drive 10.5 ft. back to Initiation line
   11. Rev Shooter to Initiation line speed
   12. Run shooter for 5 seconds with index